

OpenFst: An Open-Source, Weighted Finite-State Transducer Library and its Applications to Speech and Language

Part II. *Library Use and Design*

Overview

1. FST Construction

- File Representation
- Compiling, Printing, Drawing FSTs
- C++ Construction

2. FST Component Classes

- Arc Design
- Weight Design

3. FST Operations

- Rational Operations
- Elementary Unary Operations
- Binary Operations
- Optimization Operations
- Normalization Operations
- Search Operations
- Traversal Operations

- Examples

4. FST Class Design

- Fst Design
- State Iterator Design
- Arc Iterator Design
- Examples

5. FST Operations Design

- Destructive/Constructive Operations
- Lazy Operations
- Alternative Transition Representations
- Composition Design - Matchers

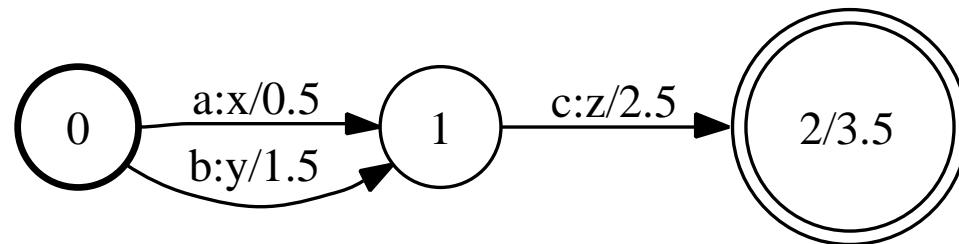
Finite-State Transducer Construction

Input Methods:

- Finite-state transducer:
 - Textual transducer file representation
 - C++ code
 - Graphical user interface
- Regular expressions
- “Context-free” rules
- “Context-dependent” rules

FST Textual File Representation

- **Graphical Representation** (T.ps):



- **Transducer File** (T.txt):

0	1	a	x	0.5
0	1	b	y	1.5
1	2	c	z	2.5
2	3.5			

- **Input Symbols File** (`T.isyms`):

a 1

b 2

c 3

- **Output Symbols File** (`T.osyms`):

x 1

y 2

z 3

Compiling, Printing, Reading, and Writing FSTs

- **Compiling**

```
fstcompile -isymbols=T.isyms -osymbols=T.osyms T.txt T.fst
```

- **Printing**

```
fstprint -isymbols=T.isyms -osymbols=T.osyms T.fst >T.txt
```

- **Drawing**

```
fstdraw -isymbols=T.isyms -osymbols=T.osyms T.fst >T.dot
```

- **Reading**

```
Fst<Arc> *fst = Fst<Arc>::Read("T.fst")
```

- **Writing**

```
fst.Write("T.fst")
```

C++ FST Construction

```
// A vector FST is a general mutable FST
VectorFst<StdArc> fst;

// Add state 0 to the initially empty FST and make it the start state
fst.AddState(); // 1st state will be state 0 (returned by AddState)
fst.SetStart(0); // arg is state ID

// Add two arcs exiting state 0
// Arc constructor args: ilabel, olabel, weight, dest state ID
fst.AddArc(0, StdArc(1, 1, 0.5, 1)); // 1st arg is src state ID
fst.AddArc(0, StdArc(2, 2, 1.5, 1));

// Add state 1 and its arc
fst.AddState();
fst.AddArc(1, StdArc(3, 3, 2.5, 2));

// Add state 2 and set its final weight
fst.AddState();
fst.SetFinal(2, 3.5); // 1st arg is state ID, 2nd arg weight
```

OpenFst Design: Arc (transition)

Labels and states may be any integral type; weights may be any class that forms a semiring:

```
struct StdArc {  
    typedef int Label;  
    typedef TropicalWeight Weight;  
    typedef int StateId;  
  
    Label ilabel;           // Transition input label  
    Label olabel;          // Transition output label  
    Weight weight;         // Transition weight  
    StateId nextstate;    // Transition destination state  
};
```

OpenFst Design: Tropical Weight

A Weight class holds the set element and provides the semiring operations:

```
class TropicalWeight {  
public:  
    TropicalWeight(float f) : value_(f) {}  
    static TropicalWeight Zero() { return TropicalWeight(kPositiveInfinity); }  
    static TropicalWeight One() { return TropicalWeight(0.0); }  
private:  
    float value_;  
};  
  
TropicalWeight Plus(TropicalWeight x, TropicalWeight y) {  
    return w1.value_ < w2.value_ ? w1 : w2;  
};
```

Similarly, e.g. LogWeight and MinMaxWeight are defined.

OpenFst Design: Product Weight

This template allows easily creating the product semiring from two (or more) semirings.

```
template <typename W1, typename W2>
class ProductWeight {
public:
    ProductWeight(W1 w1, W2 w2) : value1_(w1), value2_(w2) {}
    static ProductWeight<W1, W2> Zero() {
        return ProductWeight(W1::Zero(), W2::Zero());
    }
    static ProductWeight<W1, W2> One() {
        return ProductWeight(W1::One(), W2::One());
    }
private:
    float value1_;
    float value2_;
};
```

```
template <typename W1, typename W2>
ProductWeight<W1, W2> Plus(ProductWeight<W1, W2> x, ProductWeight<W1, W2> y) {
    return ProductWeight<W1, W2>(
        Plus(x.value1_, y.value1_),
        Plus(x.value2_, y.value2_));
}
```

Similarly, e.g. `LexicographicWeight` is defined.

Operation Implementation Types

- **Destructive:** Modifies input; $O(|Q| + |E|)$:

```
StdFst *input = StdFst::Read("input.fst");
Invert(input);
```

- **Constructive:** Writes to output; $O(|Q| + |E|)$:

```
StdFst *input = StdFst::Read("input.fst");
StdVectorFst output;
ShortestPath(input, &output);
```

- **Lazy (or Delayed):** Creates new Fst; $O(|Q_{visit}| + |E_{visit}|)$:

```
StdFst *input = StdFst::Read("input.fst");
StdFst *output = new StdInvertFst(input);
```

Lazy implementations are useful in applications where the whole machine may not be visited, e.g. Dijkstra (positive weights), pruned search.

Rational Operations

OPERATION	USAGE	DESCRIPTION
Union (Sum)	Union(&A, B); UnionFst<Arc>(A, B); fstunion a.fst b.fst out.fst	contains strings in A and B
Concat (Product)	Concat(&A, B); Concat(A, &B); ConcatFst<Arc>(A, B); fstconcat a.fst b.fst out.fst	contains strings in A followed by B
Closure	Closure(&A, type); ClosureFst<Arc>(A, type); fstclosure in.fst out.fst	$A^* = \{\epsilon\} \cup A \cup AA \cup \dots$

Elementary Unary Operations

OPERATION	USAGE	DESCRIPTION
Reverse	Reverse(A, &B);	reversed strings of A
Invert	Invert(&A); InvertFst<Arc>(A); fstinvert in.fst out.fst	inverse binary relation; swaps input and output labels
Project	Project(&A, type); ProjectFst<Arc>(A, type); fstproject [-project_output] in.fst out.fsa	creates acceptor of just the input or output strings

Fundamental Binary Operations

OPERATION	USAGE	DESCRIPTION
Compose	<code>Compose(A, B, &C);</code> <code>ComposeFst<Arc>(A, B);</code> <code>fstcompose a.fst b.fst out.fst</code>	composition of binary relations
Intersect	<code>Intersect(A, B, &C);</code> <code>IntersectFst<Arc>(A, B);</code> <code>fstintersect a.fsa b.fsa out.fsa</code>	contains strings in both A and B
Difference	<code>Difference(A, B, &C);</code> <code>DifferenceFst<Arc>(A, B);</code> <code>fstdifference a.fsa b.dfa out.fsa</code>	contains strings in A but not in B; B unweighted

Optimization Operations

OPERATION	USAGE	DESCRIPTION
Connect	Connect(&A);	Removes useless states and arcs
RmEpsilon	RmEpsilon(&A); RmEpsilonFst<Arc>(A); fstrmepsilon in.fst out.fst	Equiv. ϵ -free transducer
Determinize	Determinize(A, &B); DeterminizeFst<Arc>(A); fstdeterminize in.fst out.fst	Equiv. deterministic transducer
Minimize	Minimize(&A); Minimize(&A, &B); fstminimize in.fst out1.fst [out2.fst]	Equiv. minimal det. transducer

Normalization Operations

OPERATION	USAGE	DESCRIPTION
TopSort	TopSort(&A); fsttopsort in.fst out.fst	Topologically sorts an acyclic FST
ArcSort	ArcSort(&A, compare; fstarcsort [-sort-type=\$t] in.fst out.fst	Sorts state's arcs given an order relation
Push	Push<Arc, Type>(&A, flags); fstpush [-flags] in.fst out.fst	Creates equiv. pushed/stochastic FST
EpsNormalize	EpsNormalize(A, &B, type); fstepsnormalize [-eps_norm_output] in.fst out.fst	Places path ϵ 's after non- ϵ 's
Synchronize	Synchronizej(A, &B); SynchronizeFst<Arc>(A); fstsyncronize in.fst out.fst	Produces monotone epsilon delay

Search Operations

OPERATION	USAGE	DESCRIPTION
ShortestPath	<code>ShortestPath(A, &B, nshortest=1);</code> <code>fstshortestpath [-nshortest=\$n] in.fst out.fst</code>	N-shortest paths
ShortestDistance	<code>ShortestDistance(A, &distance);</code> <code>ShortestDistance(A, &distance, true);</code> <code>fstshortestdistance [-reverse] in.fst [dist.txt]</code>	Shortest distance from initial states Shortest distance to final states
Prune	<code>Prune(&A, threshold);</code> <code>fstprune [-weight=\$w] in.fst out.fst</code>	Prunes states and arcs by path weight

Traversal Operations

OPERATION	USAGE	DESCRIPTION
Map	Map(&A, mapper); Map(A, &B, mapper); MapFst<IArc, OArc, Mapper>(A, mapper);	Transforms arcs in an FST
Visit	Visit(A, &visitor, &queue);	Visits FST using queue disc.

- **Mapper**: Class with method:
 - `OArc operator()(const IArc &arc);`
- **Visitor**: Class with methods e.g.:
 - `bool WhiteArc(StateId s, const Arc &arc);,`
 - `bool GreyArc(StateId s, const Arc &arc);,`
 - `bool BlackArc(StateId s, const Arc &arc);`
- **Queue**: Class with methods e.g.:
 - `bool Enqueue(StateId s);`
 - `StateId Head();`
 - `void Dequeue();`
 - `bool Empty();`

Example: FST Application - Shell-Level

```
# The FSTs must be sorted along the dimensions they will be joined.  
# In fact, only one needs to be so sorted.  
# This could have instead been done for "model.fst" when it was  
created.  
  
$ fstarcsort --sort_type=olabel input.fst input_sorted.fst  
$ fstarcsort --sort_type=ilabel model.fst model_sorted.fst  
  
# Creates the composed FST  
$ fstcompose input_sorted.fst model_sorted.fst comp.fst  
  
# Just keeps the output label  
$ fstproject --project_output comp.fst result.fst  
  
# Do it all in a single command line  
$ fstarcsort --sort_type=ilabel model.fst |  
fstcompose input.fst - | fstproject --project_output result.fst
```

Example: FST Application - C++

```
// Reads in an input FST.  
StdFst *input = StdFst::Read("input.fst");  
  
// Reads in the transduction model.  
StdFst *model = StdFst::Read("model.fst");  
  
// The FSTs must be sorted along the dimensions they will be joined.  
// In fact, only one needs to be so sorted.  
// This could have instead been done for "model.fst" when it was created.  
ArcSort(input, StdOLabelCompare());  
ArcSort(model, StdILabelCompare());  
  
// Container for composition result.  
StdVectorFst result;  
  
// Create the composed FST  
Compose(*input, *model, &result);  
  
// Just keeps the output labels  
Project(&result, PROJECT_OUTPUT);
```

Example: Shortest-Distance with Various Semirings

- Tropical Semiring:

```
Fst<StdArc> *input = Fst<StdArc>::Read("input.fst");
vector<StdArc::Weight> distance;
ShortestDistance(*input, &distance);
```

- Log Semiring:

```
Fst<LogArc> *input = Fst::Read("input.fst");
vector<LogArc::Weight> distance;
ShortestDistance(*input, &distance);
```

- Right String Semiring:

```
typedef StringArc<TropicalWeight, STRING_RIGHT> SA;
Fst<SA> *input = Fst::Read("input.fst");
vector<SA::Weight> distance;
ShortestDistance(*input, &distance);
```

- Left String Semiring:

ERROR: ShortestDistance: Weights need to be right distributive

Example: Expectation Semiring

Let \mathbb{K} denote $(\mathbb{R} \cup \{+\infty, -\infty\}) \times (\mathbb{R} \cup \{+\infty, -\infty\})$. For pairs (x_1, y_1) and (x_2, y_2) in \mathbb{K} , define the following :

$$\begin{aligned}(x_1, y_1) \oplus (x_2, y_2) &= (x_1 + x_2, y_1 + y_2) \\(x_1, y_1) \otimes (x_2, y_2) &= (x_1 x_2, x_1 y_2 + x_2 y_1)\end{aligned}$$

The system $(\mathbb{K}, \oplus, \otimes, (0, 0), (1, 0))$ defines a commutative semiring.

This semiring combined with the composition and shortest-distance algorithms has been used e.g. to compute the relative entropy between probabilistic automata [C. Cortes, M. Mohri, A. Rastogi, and M. Riley. On the Computation of the Relative Entropy of Probabilistic Automata. *International Journal of Foundations of Computer Science*, 2007.]:

$$D(A\|B) = \sum_x \llbracket A \rrbracket(x) \log \llbracket A \rrbracket(x) - \sum_x \llbracket A \rrbracket(x) \log \llbracket B \rrbracket(x).$$

This algorithm is trivially implemented in the OpenFst Library.

OpenFst Design: Fst (generic)

```
template <class Arc>
class Fst {
public:
    virtual StateId Start() const = 0;           // Initial state
    virtual Weight Final(StateId) const = 0;       // State's final weight
    static Fst<Arc> *Read(const string filename);
}
```

OpenFst Design: State Iterator

```
template <class F>
class StateIterator {
public:
    explicit StateIterator(const F &fst);
    virtual ~StateIterator();
    virtual bool Done();                                // States exhausted?
    virtual StateId Value() const;                     // Current state Id
    virtual void Next();                               // Advance a state
    virtual void Reset();                             // Start over
}
```

OpenFst Design: Arc Iterator

```
template <class F>
class ArcIterator {
public:
    explicit ArcIterator(const F &fst, StateId s);
    virtual ~ArcIterator();
    virtual bool Done();                                // Arcs exhausted?
    virtual const Arc &Value() const;                  // Current arc
    virtual void Next();                               // Advance an arc
    virtual void Reset();                            // Start over
    virtual void Seek(size_t a);                     // Random access
}
```

OpenFst Design: MutableFst

```
template <class Arc>
class MutableFst : public Fst<Arc> {
public:
    void SetStart(StateId s);                      // Set initial state
    void SetFinal(StateId s, Weight w);            // Set final weight
    void AddState();                                // Add a state
    void AddArc(StateId s, const Arc &arc);        // Add an arc
}
```

OpenFst Design: Mutable Arc Iterator

```
template <class F>
class MutableArcIterator {
public:
    explicit MutableArcIterator(F *fst, StateId s);
    virtual ~MutableArcIterator();
    virtual bool Done();                                // Arcs exhausted?
    virtual const Arc &Value() const;                  // Current arc
    virtual void Next();                               // Advance an arc
    virtual void Reset();                            // Start over
    virtual void Seek(size_t a);                     // Random access
    virtual void SetValue(const Arc &arc);           // Set current arc
}
```

OpenFst Design: Invert (Destructive)

```
template <class Arc> void Invert(MutableFst<Arc> *fst) {
    for (StateIterator< MutableFst<Arc> > siter(*fst);
        !siter.Done();
        siter.Next()) {
        StateId s = siter.Value();
        for (MutableArcIterator< MutableFst<Arc> > aiter(fst, s);
            !aiter.Done();
            aiter.Next()) {
            Arc arc = aiter.Value();
            Label l = arc.ilabel;
            arc.ilabel = arc.olabel;
            arc.olabel = l;
            aiter.SetValue(arc);
        }
    }
}
```

Easier to use Map for this case.

OpenFst Design: Invert (Lazy)

```
template <class Arc> class InvertFst : public Fst<Arc> {
public:
    virtual StateId Start() const { return fst_->Start(); }
    ...
private:
    const Fst<Arc> *fst_;
}

template <class F> Arc ArcIterator<F>::Value() const {
    Arc arc = arcs_[i_];
    Label l = arc.ilabel;
    arc.ilabel = arc.olabel;
    arc.olabel = l;
    return arc;
}
```

Easier to use `MapFst` for this case.

Transition Representation

- We have represented a transition as:

$$e \in Q \times (\Sigma \cup \{\epsilon\}) \times (\Delta \cup \{\epsilon\}) \times \mathbb{K} \times Q.$$

- Treats input and output symmetrically
 - Space-efficient single output-label per transition
 - Natural representation for composition algorithm
- Alternative representation of a transition:

$$e \in Q \times (\Sigma \cup \{\epsilon\}) \times \Delta^* \times \mathbb{K} \times Q.$$

or equivalently,

$$e \in Q \times (\Sigma \cup \{\epsilon\}) \times \mathbb{K}' \times Q, \quad \mathbb{K}' = \Delta^* \times \mathbb{K}.$$

- Treats string and \mathbb{K} outputs uniformly
- Natural representation for weighted transducer determinization, minimization, label pushing, and epsilon normalization.

Operations Using Alternative Transition Representation

- We can use the alternative transition representation with:

```
typedef ProductWeight<StringWeight, TropicalWeight> GallicWeight;
```

- Weighted transducer determinization becomes:

```
Fst<StdArc> *input = Fst::Read("input.fst");
// Converts into alternative transition representation
MapFst<StdArc, GallicArc> gallic(*input, ToGallicMapper);
WeightedDeterminizeFst<GallicArc> det(gallic);
// Ensures only one output label per transition (functional input)
FactorWeightFst<GallicArc> factor(det);
// Converts back from alternative transition representation
MapFst<GallicArc> result(factor, FromGallicMapper);
```

- Efficiency is not sacrificed given the lazy computation and an efficient string semiring representation.

- Weighted transducer minimization, label pushing and epsilon normalization are similarly implemented easily using the generic (acceptor) weighted minimization, weight pushing, and epsilon removal algorithms.

Operation Options

- Example Options:

```
typedef RhoMatcher< SortedMatcher<StdFst> > RM;
```

```
ComposeFstOptions<StdArc, RM> opts;
```

```
opts.matcher1 = new RM(fst1, MATCH_NONE, kNoLabel);
```

```
opts.matcher2 = new RM(fst2, MATCH_INPUT, kNoLabel);
```

```
StdComposeFst cfst(fst1, fst2, opts);
```

- Many operations optionally take similar option arguments.

Composition: Matcher Design

- Matchers can find and iterate through requested labels at FST states; principal use in composition matching.
- **Matcher Form:**

```
template <class F>
class Matcher {
    typedef typename F::Arc Arc;

public:
    void SetState(StateId s);           // Specifies current state
    bool Find(Label label);            // Checks state for match to label
    bool Done() const;                 // No more matches
    const Arc& Value() const;          // Current arc
    void Next();                      // Advance to next arc
};
```

Matchers

- Predefined Matchers:

NAME	DESCRIPTION
SortedMatcher	Binary search on sorted input
RhoMatcher<M>	ρ symbol handling; templated on underlying matcher
SigmaMatcher<M>	σ symbol handling; templated on underlying matcher
PhiMatcher<M>	φ symbol handling; templated on underlying matcher

- The *special symbols* referenced above behave as:

	CONSUMES NO SYMBOL	CONSUMES SYMBOL
MATCHES ALL	ϵ	σ
MATCHES REST	φ	ρ